



GN010 Application Note  
EZDrive<sup>SM</sup> Solution for GaN Systems' E-HEMT

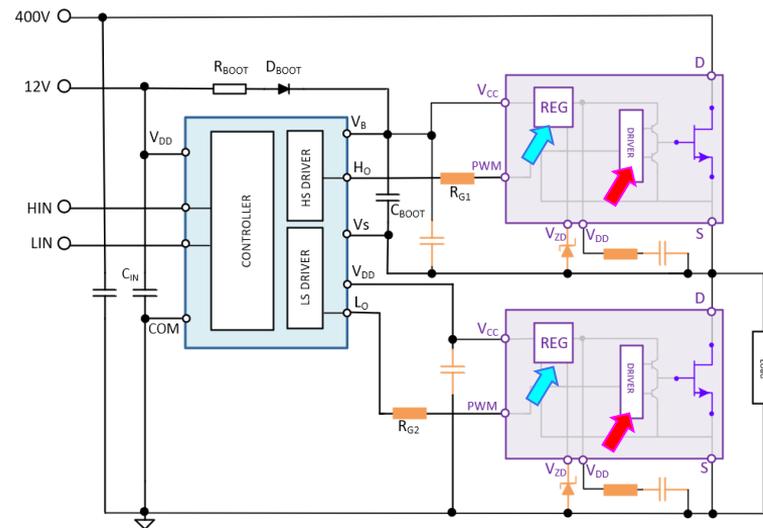
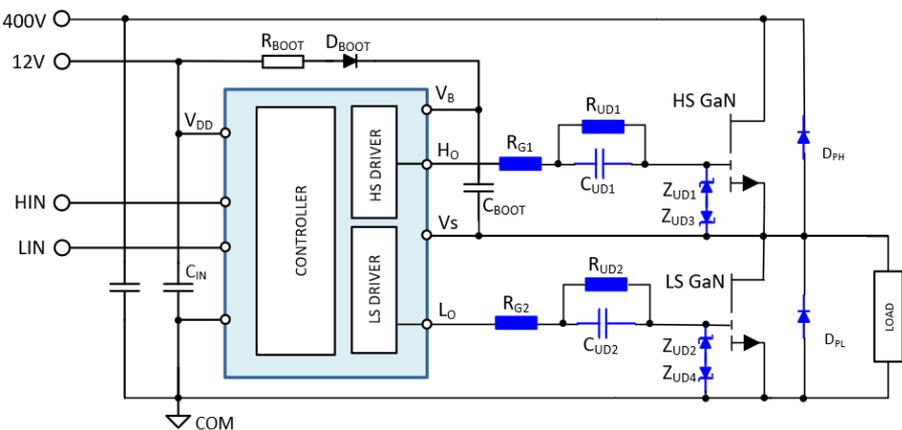
December 21, 2018

GaN Systems' **EZDrive<sup>SM</sup>** circuit is a low cost, easy way to implement a **GaN driving circuit**. It is adaptable to any power level, any frequency, and any LLC and PFC controller. The EZDrive<sup>SM</sup> circuit provides design control for the optimization of efficiency and EMI.

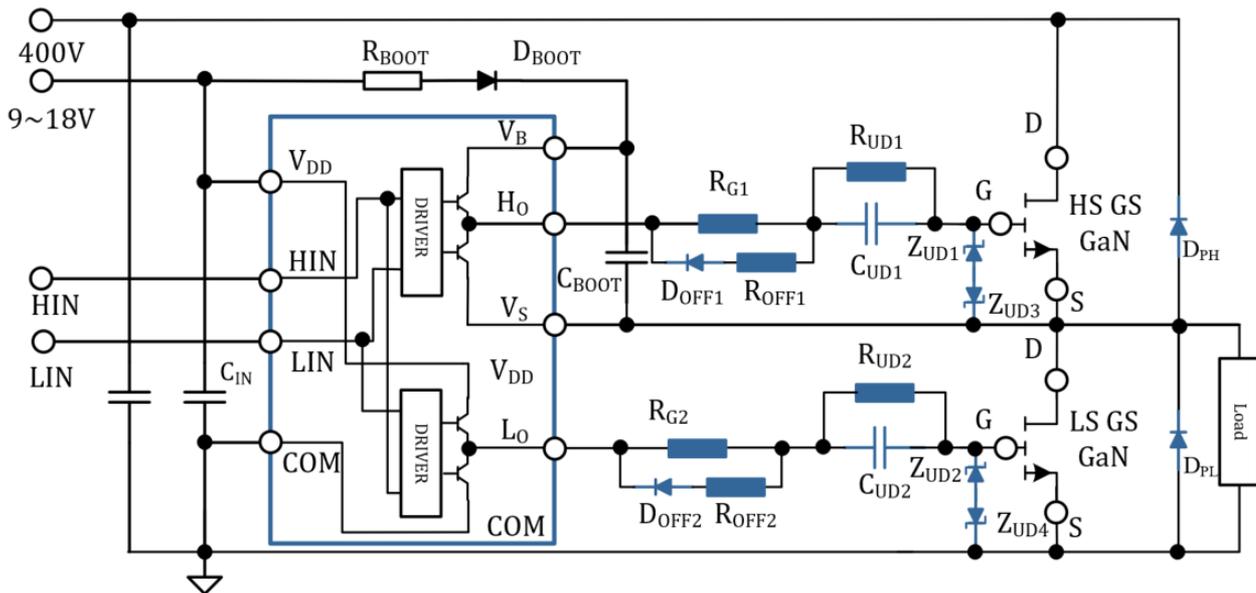
The **EZDrive<sup>SM</sup>** circuit allows the use of a standard MOSFET controller with integrated driver to drive GaN Systems' E-HEMTs. The table below summarizes the advantages of this circuit.

Application Considerations	Silicon MOSFETs	Monolithic-integrated Driver GaN	GaN Systems E-HEMTs
Total BoM Cost	Lowest	Highest	Low
Choice of devices to optimize design	Widest	Narrow	Wide range from 25 mΩ to 500 mΩ
Utilize controller driver, eliminate driver redundancy, ease-of-use	<ul style="list-style-type: none"> <li>• Driver integrated in controller</li> <li>• No redundant drivers</li> </ul>	<ul style="list-style-type: none"> <li>• Driver integrated in controller</li> <li>• Redundant drivers in GaN device</li> </ul>	<ul style="list-style-type: none"> <li>• Driver integrated in controller</li> <li>• No redundant drivers</li> </ul>
EMI control	Adjustable EMI control with gate resistor $R_G$	Fixed – cannot control turn-off slew rate	Adjustable EMI control with gate resistor $R_G$
Power density	Low	High	High

## GaN Transistors + EZDrive<sup>SM</sup> circuit vs Monolithic-integrated GaN transistors + drivers



<p>Fewest circuit blocks + standard componentry (<b>cost effective</b>)</p>	<p>Integrated = <span style="color: red;">↗</span> 2 extra Drivers + <span style="color: blue;">↗</span> 2 extra LDOs (<b>higher cost and complexity</b>)</p>
<p>Control Turn-on, turn-off, negative drive (<b>optimized EMI and efficiency</b>)</p>	<p>Control of turn-on only (<b>sub-optimal performance</b>)</p>

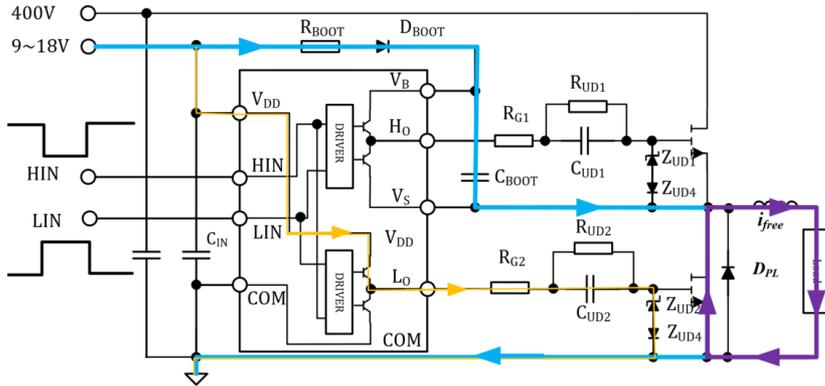


Standard componentry: GaN + MOSFET controller + discrete

- Enable controller to **drive GaN HEMT** with a **small number of external components**
- **Turn ON / OFF slew rate is controllable** with external resistors to optimize EMI
- Applies to **any controllers with single, dual, or high-side/low-side drivers**

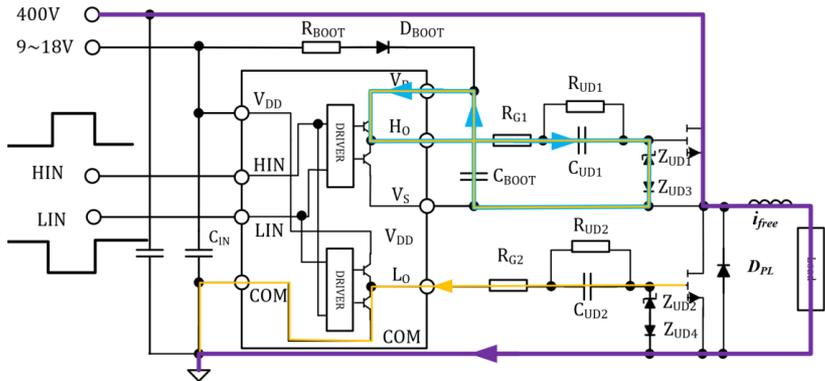
# Operation Modes of EZDrive<sup>SM</sup> Solution

## Mode 1: $C_{BOOT}$ Charging (HS GaN: off; LS GaN: on)



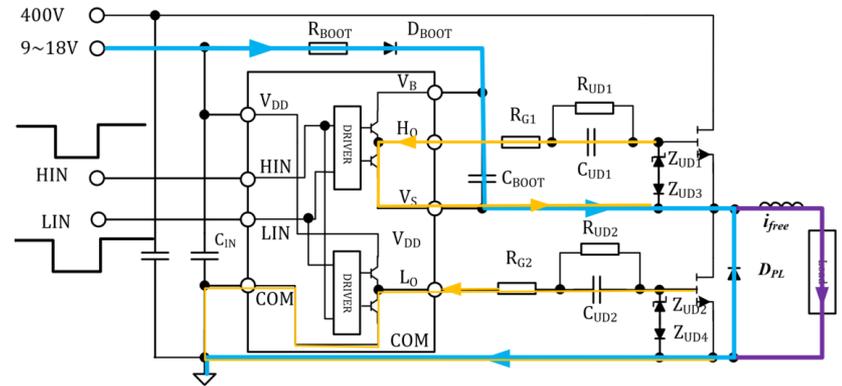
$$V_{GS\_LS} = +6V; V_{GS\_HS} = -6V$$

## Mode 3: $C_{BOOT}$ Discharging (HS GaN: on; LS GaN: off)



$$V_{GS\_LS} = -6V; V_{GS\_HS} = +6V$$

## Mode 2: $C_{BOOT}$ Charging (HS GaN: off; LS GaN: off)

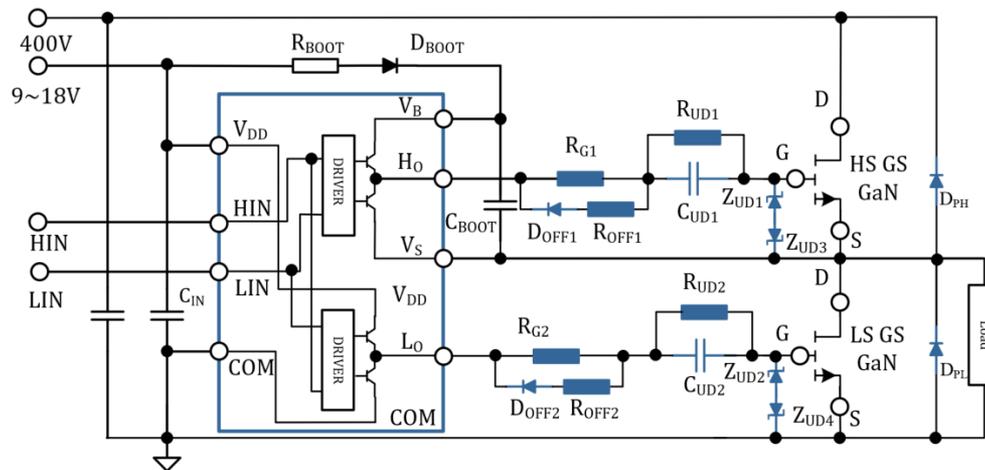


$$V_{GS\_LS} = -6V; V_{GS\_HS} = -6V$$



- EZDrive<sup>SM</sup> operation modes are **similar to** conventional non-isolated Bootstrap high side/low side driver
- Allows **wide controller driving voltage range (9~18V)**

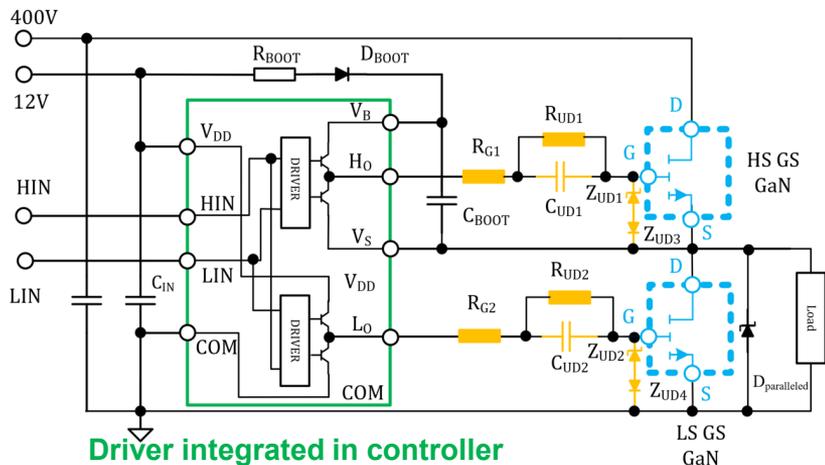
# Choosing EZDrive<sup>SM</sup> Circuit Component Values



Symbol	Rec. Value	Function
$R_{G1,2}$	5-10 $\Omega$	Control turn ON speed
$R_{UD1,2}$	$\sim 10$ k $\Omega$	Keep the driving voltage
$C_{UD1,2}$	$\sim 47$ nF	Hold negative voltage for turning off
$Z_{UD1,2}$	5.6 V Zener	Clamp the positive gate voltage
$Z_{UD3,4}$	9.1 V Zener	Clamp the negative gate voltage
$D_{PL}$	600V FRD 1A	Avoid $C_{BOOT}$ overcharging, for reduced low side $P_{DT}$ (Note 1)
$D_{PH}$	600V FRD 1A	Optional for reduced high side $P_{DT}$ (Note 1)
$D_{OFF1,2}$	20V DIODE 1A	Enable independent turn-off speed control
$R_{OFF1,2}$	0 $\Omega$	Control turn-off speed

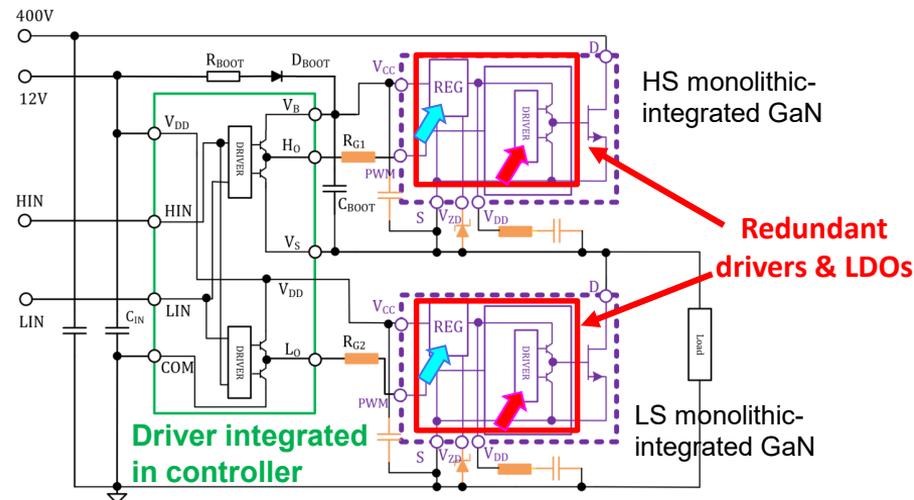
Note 1:  $D_{PH}$  and  $D_{PL}$  are not required if the controller has internal Sync Boot function to regulate bootstrap voltage

## GaN Systems EZDrive<sup>SM</sup> Solution



Driver integrated in controller

## Monolithic-integrated Solution



Driver integrated in controller

HS monolithic-integrated GaN

Redundant drivers & LDOs

LS monolithic-integrated GaN

HV HB Bootstrap Driver Simplified Diagram

External Components

GaN Systems' GaN

Integrated GaN + drivers

Fewest circuit blocks + standard componentry  
(cost effective)

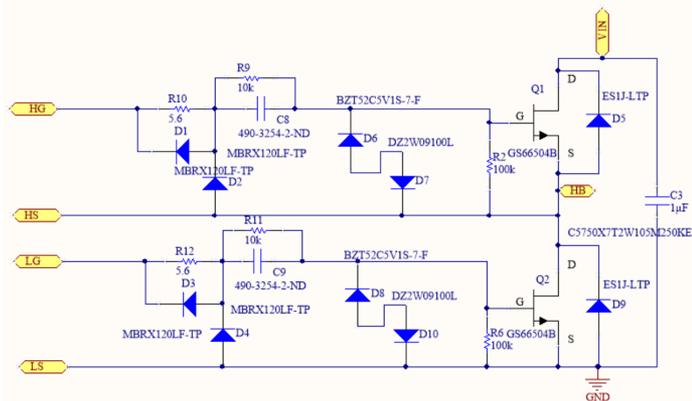
Integrated = 2 extra Drivers + 2 extra LDOs  
(higher cost and complexity)

Control Turn-on, turn-off, negative drive  
(optimized EMI and efficiency)

Control of turn-on only  
(sub-optimal performance)

Transistor	PFC/LLC Controller	External Driver	Integrated Driver in FETs	Multisource Devices	Transistor Range
<b>Silicon MOSFET</b>	Several available from ON Semi, TI, ST Micro and others. Examples include: <u>PFC</u> • NCP1616, NCP1615, L6562A <u>LLC</u> • NCP1399, NCP13992	NO	NO	YES	Widest
<b>Monolithic-integrated GaN</b>		NO	YES	NO	Narrow
<b>GaN Systems</b>		NO	NO	YES	25, 50, 67, 100, 150, 200, 225, 500 mΩ

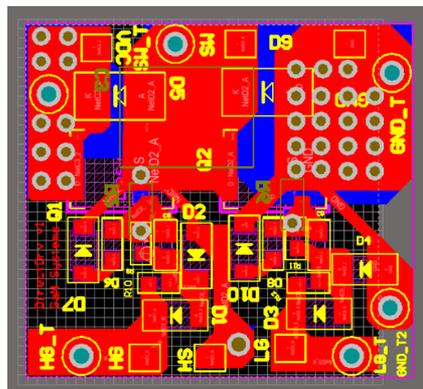
- Driving GaN transistors directly with controllers **simplifies and reduces the cost** of the circuit
- Using discrete GaN transistors provides customers
  - **a wide range of products**
  - **multiple sources of GaN devices**



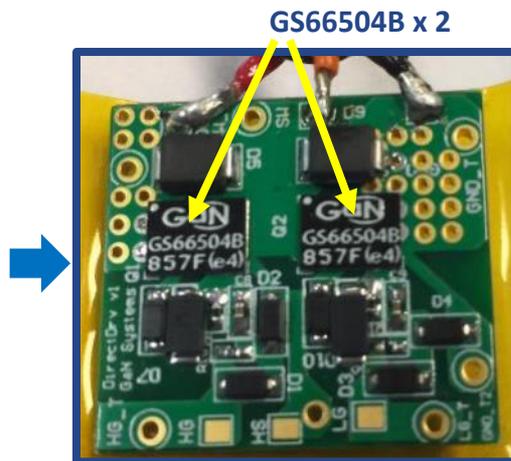
Schematic of EZDrive<sup>SM</sup> in Half Bridge



Test board (Top View)



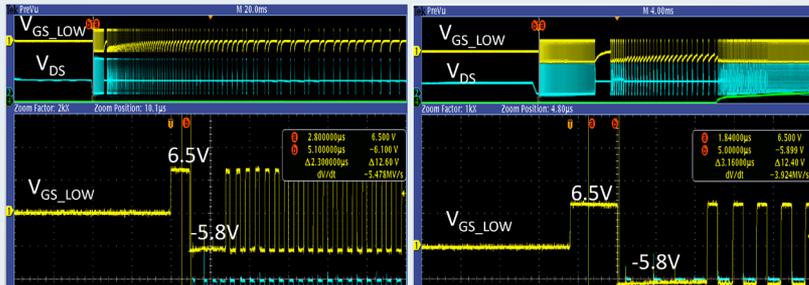
Layout of Half Bridge EZDrive<sup>SM</sup>



EZDrive<sup>SM</sup> Daughter Card



Test board (Bottom View)



@ no load (I<sub>out</sub>=0A)

@ full load (I<sub>out</sub>=20A)

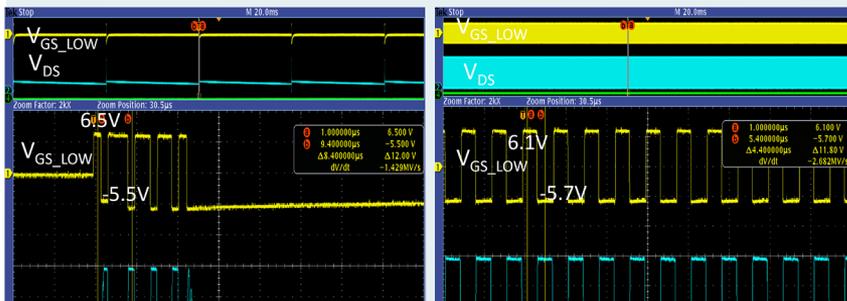
## Start-up Process



0A to 20A

20A to 0A

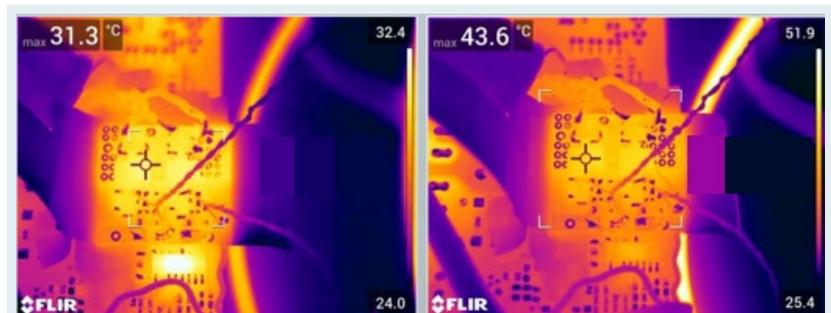
## Load Step Change



@ no load (I<sub>out</sub>=0A)

@ full load (I<sub>out</sub>=20A)

## Static Operation



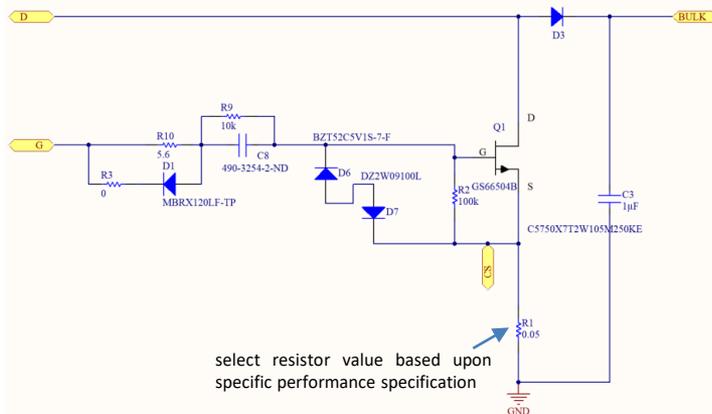
@ half load (10A)

@ full load (20A)

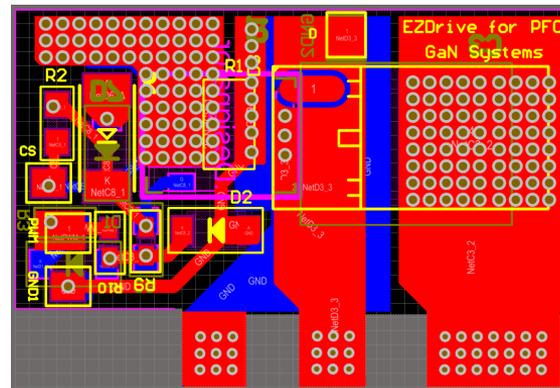
## Temperature Distribution

- **No overshoot/undershoot** on V<sub>GS</sub> & V<sub>DS</sub> in all operating conditions
- **Low operating temperatures**

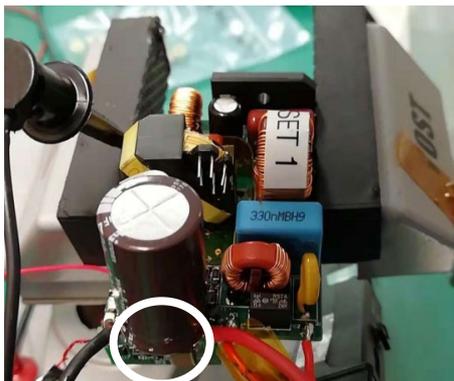
### EZDrive<sup>SM</sup> PFC daughter card schematic



### EZDrive<sup>SM</sup> PFC daughter card



### PFC with transition-mode controller L6562A (Top View)



### PFC with transition-mode controller L6562A (Side View)



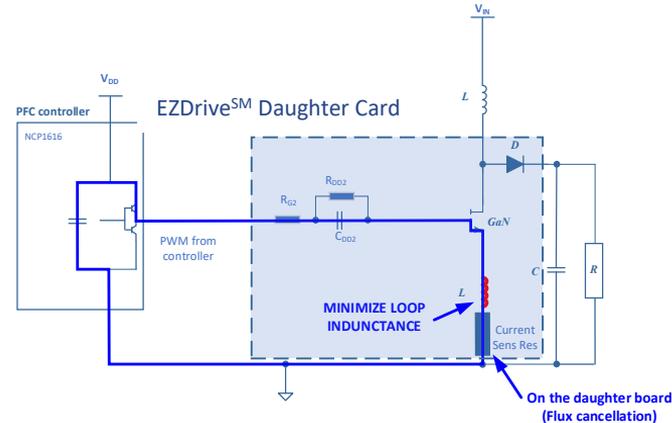
### 650V 15A GaN E-HEMT: GS66504B



top



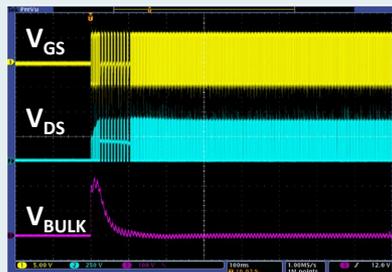
bottom



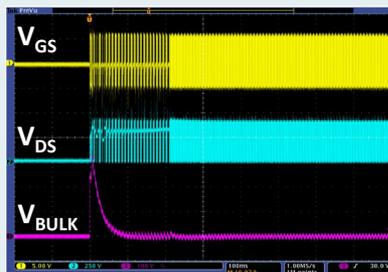
Recommendations for PFC daughter cards Layout	Objectives
<ul style="list-style-type: none"> <li>• Shorten the trace length between the sensing resistor and Power GND</li> </ul>	Reduce trace inductance
<ul style="list-style-type: none"> <li>• Put the sensing resistor and GaN back-to-back on the 2-layer board</li> <li>• 2-layer PCB is the low cost solution, using 4-layer PCB will further reduce the common inductance and get better thermal performance</li> </ul>	Flux cancellation - reduce the mutual inductance
<ul style="list-style-type: none"> <li>• SMD current sensing resistor</li> </ul>	Reduce the parasitic inductance
<ul style="list-style-type: none"> <li>• Avoid using probe with long ground wire to sense the signals, isolation probe for VDS measurements is recommended (Note 3)</li> </ul>	Avoid introducing the parasitics from the measurement

Note 3: more details is available in app note GN003 "Measurement Techniques for High-Speed GaN E-HEMTs"  
[https://gansystems.com/wp-content/uploads/2018/08/GN003-Measurement-Techniques-for-High-Speed-GaN-E-HEMTs\\_20180816.pdf](https://gansystems.com/wp-content/uploads/2018/08/GN003-Measurement-Techniques-for-High-Speed-GaN-E-HEMTs_20180816.pdf)

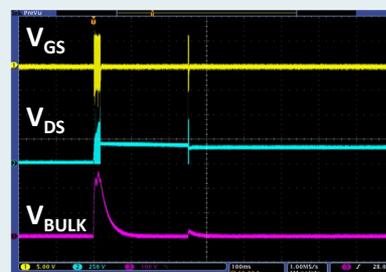
## Start-up Process



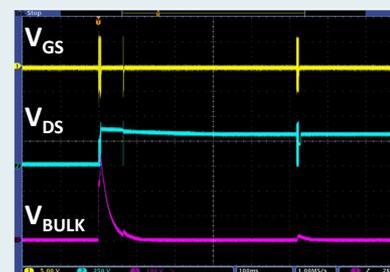
@ 110Vac & full load (400V,0.5A)



@ 220Vac & full load (400V,0.5A)

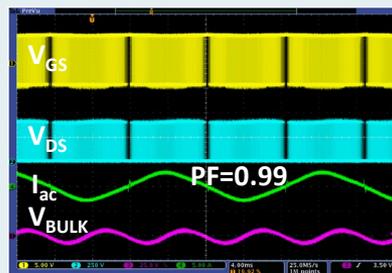


@ 110Vac & no load (400V,0A)

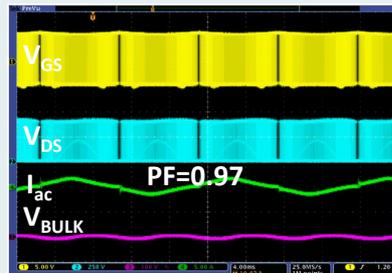


@ 220Vac & no load (400V,0A)

## Static Operation



@ 110Vac & full load (400V,0.5A)

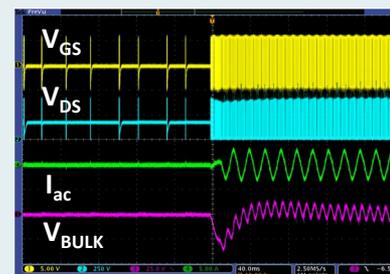


@ 220Vac & full load (400V,0.5A)

## Load Step Change



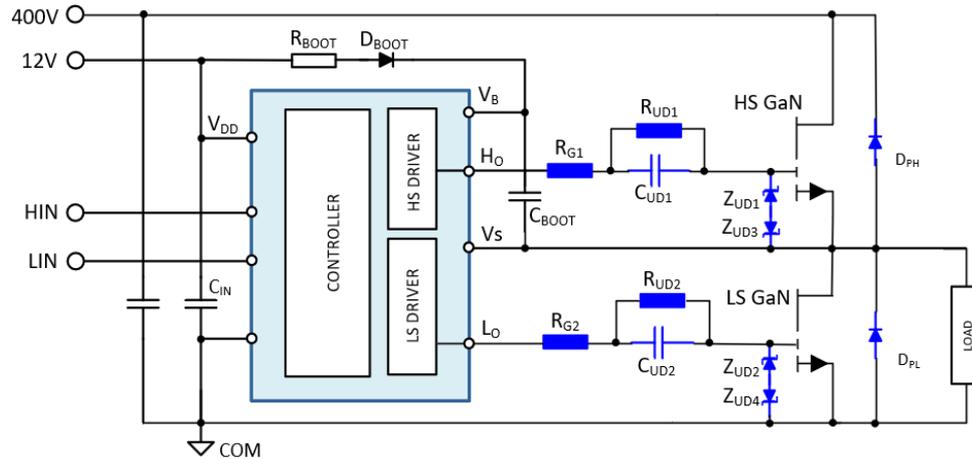
Full load to no load (0.5A to 0A)



No load to full load (0A to 0.5A)

- **No overshoot/undershoot** on  $V_{GS}$  &  $V_{DS}$  in all operating conditions

- Universally converts any IC controller/driver to properly drive GaN Systems transistors
- Eliminates the redundant GaN drivers & LDOs of a monolithic integrated driver GaN device
- Turn ON / OFF slew rate is controllable with external resistors for complete control of EMI
- Applies to single, dual, or high-side/low-side controllers with drivers



- **Simple**
- **Eliminates drivers**
- **Higher power density**
- **Lower Cost**



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